

FXLA102

Low Voltage Dual Supply 2-Bit Voltage Translator with Configurable Voltage Supplies and Signal Levels, 3-State Outputs, and Auto Direction Sensing

Features

- Bi-directional interface between two levels from 1.1V to 3.6V.
- Fully configurable: Inputs and outputs track V_{CC} level.
- Non-preferential power-up; either V_{CC} may be powered-up first.
- Outputs remain in 3-state until active V_{CC} level is reached.
- Outputs switch to 3-state if either V_{CC} is at GND.
- Power off protection
- Bushold on data inputs eliminates the need for pull-up or pull-down resistors
- Control input (\overline{OE}) is referenced to V_{CCA} voltage.
- Packaged in 8-terminal leadless MicroPak (1.6mm x 1.6mm)
- Direction control not needed.
- 100 Mbps throughput when translating between 1.8V and 2.5V.
- ESD protection exceeds:
 - 15kV HBM (B port I/O to GND) (per JESD22-A114 & Mil Std 883e 3015.7)
 - 8kV HBM (A port I/O to GND) (per JESD22-A114 & Mil Std 883e 3015.7)
 - 2kV CDM (per ESD STM 5.3)

General Description

The FXLA102 is a configurable dual-voltage-supply translator designed for both uni-directional and bi-directional voltage translation between two logic levels. The device allows translation between voltages as high as 3.6V to as low as 1.1V. The A port tracks the V_{CCA} level, and the B port tracks the V_{CCB} level. This allows for bi-directional voltage translation over a variety of voltage levels: 1.2V, 1.5V, 1.8V, 2.5V and 3.3V.

The device remains in 3-state until both VCCs reach active levels, allowing either V_{CC} to be powered-up first. Internal power down control circuits place the device in 3-state if either V_{CC} is removed.

The \overline{OE} input, when high, disables both the A and B ports by placing them in a 3-state condition. The \overline{OE} input is supplied by V_{CCA} .

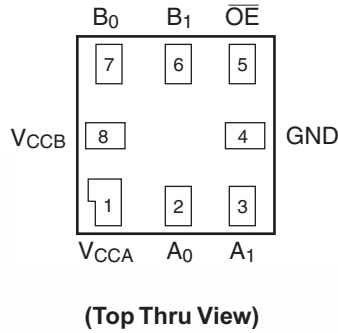
The FXLA102 supports bi-directional translation without the need for a direction control pin. The two ports of the device have auto-direction sense capability. Either port may sense an input signal and transfer it as an output signal to the other port.

Ordering Information

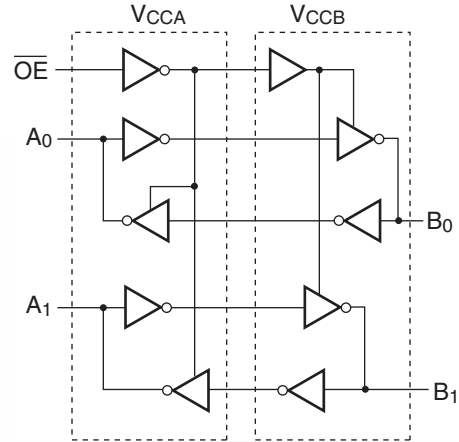
| Order Number | Package Number | Product Code Top Mark | Package Description | Supplied As |
|--------------|----------------|-----------------------|-----------------------------|---------------------------|
| FXLA102L8X | MAC08A | XF | 8-Lead MicroPak, 1.6mm Wide | 3k Units on Tape and Reel |

 All packages are lead free per JEDEC: J-STD-020B standard.

Connection Diagram



Functional Diagram



Pin Description

| Number | Name | Description |
|--------|---------------------------------|----------------------------------|
| 1 | V _{CCA} | A Side Power Supply |
| 2, 3 | A ₀ , A ₁ | A Side Inputs or 3-State Outputs |
| 4 | GND | |
| 5 | \overline{OE} | Output Enable Input |
| 6, 7 | B ₁ , B ₀ | A Side Inputs or 3-State Outputs |
| 8 | V _{CCB} | B Side Power Supply |

Function Table

| Control | Outputs |
|-----------------|------------------|
| \overline{OE} | |
| L | Normal Operation |
| H | 3-State |

H = HIGH Logic Level

L = LOW Logic Level

Power-Up/Power-Down Sequencing

FXL translators offer an advantage in that either V_{CC} may be powered up first. This benefit derives from the chip design. When either V_{CC} is at 0 volts, outputs are in a high-impedance state. The control input (\overline{OE}) is designed to track the V_{CCA} supply. A pull-up resistor tying \overline{OE} to V_{CCA} should be used to ensure that bus contention, excessive currents, or oscillations do not occur during power-up/power-down. The size of the pull-up resistor is based upon the current-sinking capability of the device driving the \overline{OE} pin.

The recommended power-up sequence is the following:

1. Apply power to the first V_{CC}.
2. Apply power to the second V_{CC}.
3. Drive the \overline{OE} input LOW to enable the device.

The recommended power-down sequence is the following:

1. Drive \overline{OE} input HIGH to disable the device.
2. Remove power from either V_{CC}.
3. Remove power from other V_{CC}.

Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Parameter | Rating |
|--------------------|--|--|
| V_{CCA}, V_{CCB} | Supply Voltage | -0.5V to +4.6V |
| V_I | DC Input Voltage I/O Port A I/O Port B Control Input (\overline{OE}) | -0.5V to +4.6V -0.5V to +4.6V -0.5V to +4.6V |
| V_O | Output Voltage ⁽²⁾ Outputs 3-STATE Outputs Active (A_n) Outputs Active (B_n) | -0.5V to +4.6V -0.5V to $V_{CCA} + 0.5V$ -0.5V to $V_{CCB} + 0.5V$ |
| I_{IK} | DC Input Diode Current @ $V_I < 0V$ | -50mA |
| I_{OK} | DC Output Diode Current @ $V_O < 0V$ $V_O > V_{CC}$ | -50mA +50mA |
| I_{OH}/I_{OL} | DC Output Source/Sink Current | -50mA / +50mA |
| I_{CC} | DC V_{CC} or Ground Current per Supply Pin | $\pm 100mA$ |
| T_{STG} | Storage Temperature Range | -65°C to +150°C |

Note:

1. I_O Absolute Maximum Rating must be observed.

Recommended Operating Conditions⁽²⁾

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to absolute maximum ratings.

| Symbol | Parameter | Rating |
|------------------------|---|--|
| V_{CCA} or V_{CCB} | Power Supply Operating | 1.1V to 3.6V |
| V_I | Input Voltage I/O Port A I/O Port B Control Inputs(\overline{OE}) | 0.0V to 3.6V 0.0V to 3.6V 0.0V to V_{CCA} |
| | Dynamic Output Current I_{OH}/I_{OL} with V_{CC} @ 3.0V to 3.6V 2.3V to 2.7V 1.65V to 1.95V 1.4V to 1.65V 1.1V to 1.4V | $\pm 12.0mA$ $\pm 8.0mA$ $\pm 5.0mA$ $\pm 3.0mA$ $\pm 2.0mA$ |
| | Static Output Current I_{OH}/I_{OL} with V_{CC} @ 1.1V to 3.6V | $\pm 4.0\mu A$ |
| T_A | Free Air Operating Temperature | -40°C to +85°C |
| $\Delta t/\Delta V$ | Maximum Input Edge Rate $V_{CCA/B} = 1.1V$ to 3.6V | 10ns/V |

Note:

2. All unused inputs and I/O pins must be held at V_{CCI} or GND.

DC Electrical Characteristics ($T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$)

| Symbol | Parameter | V _{CCA} (V) | V _{CCB} (V) | Conditions | Min. | Typ. | Max. | Units |
|------------------------------------|--------------------------------------|-------------------------|----------------------|--|-------------------------|------|-------------------------|-------|
| V _{IHA} | High Level Input Voltage | 2.7–3.6 | 1.1–3.6 | Data inputs A _n , Control Input $\overline{\text{OE}}$ | 2.0 | | | V |
| | | 2.3–2.7 | | | 1.6 | | | |
| | | 1.65–2.3 | | | 0.65 x V _{CCA} | | | |
| | | 1.4–1.65 | | | 0.65 x V _{CCA} | | | |
| | | 1.1–1.4 | | | 0.9 x V _{CCA} | | | |
| V _{IHB} | | 1.1–3.6 | 2.7–3.6 | Data Inputs B _n | 2.0 | | | V |
| | | 2.3–2.7 | | | 1.6 | | | |
| | | 1.65–2.3 | | | 0.65 x V _{CCB} | | | |
| | | 1.4–1.65 | | | 0.65 x V _{CCB} | | | |
| | | 1.1–1.4 | | | 0.9 x V _{CCB} | | | |
| V _{ILA} | Low Level Input Voltage | 2.7–3.6 | 1.1–3.6 | Data Inputs A _n , Control Input $\overline{\text{OE}}$ | | | 0.8 | V |
| | | 2.3–2.7 | | | | | 0.7 | |
| | | 1.65–2.3 | | | | | 0.35 x V _{CCA} | |
| | | 1.4–1.65 | | | | | 0.35 x V _{CCA} | |
| | | 1.1–1.4 | | | | | 0.1 x V _{CCA} | |
| V _{ILB} | | 1.1–3.6 | 2.7–3.6 | Data Inputs B _n | | | 0.8 | V |
| | | 2.3–2.7 | | | | | 0.7 | |
| | | 1.65–2.3 | | | | | 0.35 x V _{CCB} | |
| | | 1.4–1.65 | | | | | 0.35 x V _{CCB} | |
| | | 1.1–1.4 | | | | | 0.1 x V _{CCB} | |
| V _{OHA} ⁽³⁾ | High Level Output Voltage | 1.1–3.6 | 1.1–3.6 | I _{OH} = -4μA | V _{CCA} - 0.4 | | | V |
| V _{OHB} ⁽³⁾ | High Level Output Voltage | 1.1–3.6 | 1.1–3.6 | I _{OH} = -4μA | V _{CCB} - 0.4 | | | V |
| V _{OLA} ⁽³⁾ | Low Level Output Voltage | 1.1–3.6 | 1.1–3.6 | I _{OL} = 4μA | | | 0.4 | V |
| V _{OLB} ⁽³⁾ | Low Level Output Voltage | 1.1–3.6 | 1.1–3.6 | I _{OL} = 4μA | | | 0.4 | V |
| I _{I(HOLD)} | Bushold Input Minimum Drive Current | 3.0 | 3.0 | V _{IN} = 0.8V | 75.0 | | | μA |
| | | 3.0 | 3.0 | V _{IN} = 2.0V | -75.0 | | | |
| | | 2.3 | 2.3 | V _{IN} = 0.7V | 45.0 | | | |
| | | 2.3 | 2.3 | V _{IN} = 1.6V | -45.0 | | | |
| | | 1.65 | 1.65 | V _{IN} = 0.57V | 25.0 | | | |
| | | 1.65 | 1.65 | V _{IN} = 1.07V | -25.0 | | | |
| | | 1.4 | 1.4 | V _{IN} = 0.49V | 11.0 | | | |
| | | 1.4 | 1.4 | V _{IN} = 0.91V | -11.0 | | | |
| | | 1.1 | 1.1 | V _{IN} = 0.11V | | 4 | | |
| 1.1 | 1.1 | V _{IN} = 0.99V | | -4 | | | | |
| I _{I(ODH)} ⁽⁴⁾ | Bushold Input Overdrive High Current | 3.6 | 3.6 | Data Inputs A _n , B _n | 450 | | | μA |
| | | 2.7 | 2.7 | | 300 | | | |
| | | 1.95 | 1.95 | | 200 | | | |
| | | 1.6 | 1.6 | | 120 | | | |
| | | 1.4 | 1.4 | | 80 | | | |
| I _{I(ODL)} ⁽⁵⁾ | Bushold Input Overdrive Low Current | 3.6 | 3.6 | Data Inputs A _n , B _n | -450 | | | μA |
| | | 2.7 | 2.7 | | -300 | | | |
| | | 1.95 | 1.95 | | -200 | | | |
| | | 1.6 | 1.6 | | -120 | | | |
| | | 1.4 | 1.4 | | -80 | | | |

DC Electrical Characteristics ($T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$) (Continued)

| Symbol | Parameter | V _{CCA} (V) | V _{CCB} (V) | Conditions | Min. | Typ. | Max. | Units |
|--------------------------------------|---------------------------|----------------------|----------------------|---|------|------|-------|-------|
| I _I | Input Leakage Current | 1.1–3.6 | 3.6 | Control input $\overline{\text{OE}}$, V _I = V _{CCA} or GND | | | ±1.0 | μA |
| I _{OFF} | Power Off Leakage Current | 0 | 3.6 | A _n Port, V _O = 0V to 3.6V | | | ±2.0 | μA |
| | | 3.6 | 0 | B _n Port, V _O = 0V to 3.6V | | | ±2.0 | μA |
| I _{OZ} | 3-State Output Leakage | 3.6 | 3.6 | Data Outputs A _n , B _n V _O = 0V or 3.6V, $\overline{\text{OE}} = V_{IH}$ | | | ±5.0 | μA |
| | | 3.6 | 0 | Data outputs A _n , V _O = 0V or 3.6V, $\overline{\text{OE}} = \text{GND}$ | | | ±5.0 | μA |
| | | 0 | 3.6 | Data outputs B _n V _O = 0V or 3.6V, $\overline{\text{OE}} = \text{GND}$ | | | ±5.0 | μA |
| I _{CCA/B} ⁽⁶⁾⁽⁷⁾ | Quiescent Supply Current | 1.1–3.6 | 1.1–3.6 | V _I = V _{CC1} or GND, I _O = 0, $\overline{\text{OE}} = \text{GND}$ | | | 10.0 | μA |
| I _{CCZ} ⁽⁶⁾⁽⁷⁾ | Quiescent Supply Current | 1.1–3.6 | 1.1–3.6 | V _I = V _{CC1} or GND, I _O = 0, $\overline{\text{OE}} = V_{IH}$ | | | 10.0 | μA |
| I _{CCA} | Quiescent Supply Current | 0 | 1.1–3.6 | V _I = V _{CCB} or GND, I _O = 0, B-to-A Direction, $\overline{\text{OE}} = \text{GND}$ | | | -10.0 | μA |
| | | 1.1–3.6 | 0 | | | | 10.0 | μA |
| I _{CCB} | Quiescent Supply Current | 1.1–3.6 | 0 | V _I = V _{CCA} or GND, I _O = 0, A-to-B Direction, $\overline{\text{OE}} = \text{GND}$ | | | -10.0 | μA |
| | | 0 | 1.1–3.6 | | | | 10.0 | μA |

Notes:

3. This is the output voltage for static conditions. Dynamic drive specifications are given in “Dynamic Output Electrical Characteristics.”
4. An external driver must source at least the specified current to switch LOW-to-HIGH.
5. An external driver must source at least the specified current to switch HIGH-to-LOW.
6. V_{CC1} is the V_{CC} associated with the input side.
7. Reflects current per supply, V_{CCA} or V_{CCB}.

Dynamic Output Electrical Characteristics⁽⁸⁾

A Port (An)

Output Load: $C_L = 15\text{pF}$, $R_L \geq 1\text{M}\Omega$ ($C_{I/O} = 4\text{pF}$)

| Symbol | Parameter | $T_A = -40^\circ\text{C to } +85^\circ\text{C}, V_{CCA} =$ | | | | | | | | | Units |
|--------------------------|-----------------------------|--|------|--------------|------|----------------|------|--------------|------|--------------|-------|
| | | 3.0V to 3.6V | | 2.3V to 2.7V | | 1.65V to 1.95V | | 1.4V to 1.6V | | 1.1V to 1.3V | |
| | | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | |
| $t_{\text{rise}}^{(9)}$ | Output Rise Time A port | | 3.0 | | 3.5 | | 4.0 | | 5.0 | 7.5 | ns |
| $t_{\text{fall}}^{(10)}$ | Output Fall Time A port | | 3.0 | | 3.5 | | 4.0 | | 5.0 | 7.5 | ns |
| $I_{\text{OHD}}^{(9)}$ | Dynamic Output Current High | -11.4 | | -7.5 | | -4.7 | | -3.2 | | -1.7 | mA |
| $I_{\text{OLD}}^{(10)}$ | Dynamic Output Current Low | +11.4 | | +7.5 | | +4.7 | | +3.2 | | +1.7 | mA |

B Port (Bn)

Output Load: $C_L = 15\text{pF}$, $R_L \geq 1\text{M}\Omega$ ($C_{I/O} = 5\text{pF}$)

| Symbol | Parameter | $T_A = -40^\circ\text{C to } +85^\circ\text{C}, V_{CCB} =$ | | | | | | | | | Units |
|--------------------------|-----------------------------|--|------|--------------|------|----------------|------|--------------|------|--------------|-------|
| | | 3.0V to 3.6V | | 2.3V to 2.7V | | 1.65V to 1.95V | | 1.4V to 1.6V | | 1.1V to 1.3V | |
| | | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | |
| $t_{\text{rise}}^{(9)}$ | Output Rise Time B port | | 3.0 | | 3.5 | | 4.0 | | 5.0 | 7.5 | ns |
| $t_{\text{fall}}^{(10)}$ | Output Fall Time B port | | 3.0 | | 3.5 | | 4.0 | | 5.0 | 7.5 | ns |
| $I_{\text{OHD}}^{(9)}$ | Dynamic Output Current High | -12.0 | | -7.9 | | -5.0 | | -3.4 | | -1.8 | mA |
| $I_{\text{OLD}}^{(10)}$ | Dynamic Output Current Low | +12.0 | | +7.9 | | +5.0 | | +3.4 | | +1.8 | mA |

Notes:

8. Dynamic Output Characteristics are guaranteed but not tested.
9. See Figure 5.
10. See Figure 6.

AC Characteristics

$V_{CCA} = 3.0V$ to $3.6V$

| Symbol | Parameter | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | | | | | Units |
|-----------------------|--|--|------|-----------|------|-------------|------|-----------|------|-----------|---------|
| | | 3.0V–3.6V | | 2.3V–2.7V | | 1.65V–1.95V | | 1.4V–1.6V | | 1.1V–1.3V | |
| | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Typ. | |
| t_{PLH} , t_{PHL} | A to B | 0.2 | 3.5 | 0.3 | 3.9 | 0.5 | 5.4 | 0.6 | 6.8 | 10.0 | ns |
| | B to A | 0.2 | 3.5 | 0.2 | 3.8 | 0.3 | 5.0 | 0.5 | 6.0 | 7.0 | ns |
| t_{PZL} , t_{PZH} | \overline{OE} to A, \overline{OE} to B | | 1.7 | | 1.7 | | 1.7 | | 1.7 | 1.7 | μs |
| $t_{skew}^{(11)}$ | A Port, B Port | | 0.5 | | 0.5 | | 0.5 | | 1.0 | 1.0 | ns |

$V_{CCA} = 2.3V$ to $2.7V$

| Symbol | Parameter | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | | | | | Units |
|-----------------------|--|--|------|-----------|------|-------------|------|-----------|------|-----------|---------|
| | | 3.0V–3.6V | | 2.3V–2.7V | | 1.65V–1.95V | | 1.4V–1.6V | | 1.1V–1.3V | |
| | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Typ. | |
| t_{PLH} , t_{PHL} | A to B | 0.2 | 3.8 | 0.4 | 4.2 | 0.5 | 5.6 | 0.8 | 6.9 | 10.5 | ns |
| | B to A | 0.3 | 3.9 | 0.4 | 4.2 | 0.5 | 5.5 | 0.5 | 6.5 | 7.0 | ns |
| t_{PZL} , t_{PZH} | \overline{OE} to A, \overline{OE} to B | | 1.7 | | 1.7 | | 1.7 | | 1.7 | 1.7 | μs |
| $t_{skew}^{(11)}$ | A Port, B Port | | 0.5 | | 0.5 | | 0.5 | | 1.0 | 1.0 | ns |

$V_{CCA} = 1.65V$ to $1.95V$

| Symbol | Parameter | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | | | | | Units |
|-----------------------|--|--|------|-----------|------|-------------|------|-----------|------|-----------|---------|
| | | 3.0V–3.6V | | 2.3V–2.7V | | 1.65V–1.95V | | 1.4V–1.6V | | 1.1V–1.3V | |
| | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Typ. | |
| t_{PLH} , t_{PHL} | A to B | 0.3 | 5.0 | 0.5 | 5.5 | 0.8 | 6.7 | 0.9 | 7.5 | 11.0 | ns |
| | B to A | 0.5 | 5.4 | 0.5 | 5.6 | 0.8 | 6.7 | 1.0 | 7.0 | 7.0 | ns |
| t_{PZL} , t_{PZH} | \overline{OE} to A, \overline{OE} to B | | 1.7 | | 1.7 | | 1.7 | | 1.7 | 1.7 | μs |
| $t_{skew}^{(11)}$ | A Port, B Port | | 0.5 | | 0.5 | | 0.5 | | 1.0 | 1.0 | ns |

$V_{CCA} = 1.4V$ to $1.6V$

| Symbol | Parameter | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | | | | | Units |
|-----------------------|--|--|------|-----------|------|-------------|------|-----------|------|-----------|---------|
| | | 3.0V–3.6V | | 2.3V–2.7V | | 1.65V–1.95V | | 1.4V–1.6V | | 1.1V–1.3V | |
| | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Typ. | |
| t_{PLH} , t_{PHL} | A to B | 0.5 | 6.0 | 0.5 | 6.5 | 1.0 | 7.0 | 1.0 | 8.5 | 11.5 | ns |
| | B to A | 0.6 | 6.8 | 0.8 | 6.9 | 0.9 | 7.5 | 1.0 | 8.5 | 9.0 | ns |
| t_{PZL} , t_{PZH} | \overline{OE} to A, \overline{OE} to B | | 1.7 | | 1.7 | | 1.7 | | 1.7 | 1.7 | μs |
| $t_{skew}^{(11)}$ | A Port, B Port | | 1.0 | | 1.0 | | 1.0 | | 1.0 | 1.0 | ns |

Note:

11. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (An, or Bn) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW). Skew is guaranteed but not tested. See Figure 8.

AC Characteristics (Continued)

$V_{CCA} = 1.1V$ to $1.3V$

| Symbol | Parameter | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | Units |
|-----------------------|--|--|-----------|-------------|-----------|-----------|---------|
| | | 3.0V–3.6V | 2.3V–2.7V | 1.65V–1.95V | 1.4V–1.6V | 1.1V–1.3V | |
| | | Typ. | Typ. | Typ. | Typ. | Typ. | |
| t_{PLH} , t_{PHL} | A to B | 7.1 | 6.5 | 7.0 | 7.1 | 13.5 | ns |
| | B to A | 10.3 | 10.5 | 10.8 | 11.3 | 13.5 | ns |
| t_{PZL} , t_{PZH} | \overline{OE} to A, \overline{OE} to B | 1.7 | 1.7 | 1.7 | 1.7 | 1.7 | μs |
| $t_{skew}^{(11)}$ | A Port, B Port | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | ns |

Note:

11. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (An, or Bn) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW). Skew is guaranteed but not tested. See Figure 8.

Max Data Rate⁽¹²⁾⁽¹³⁾

| $V_{CCA} =$ | $T_A = -40^{\circ}C$ to $+85^{\circ}C$, $V_{CCB} =$ | | | | | Units |
|----------------|--|--------------|----------------|--------------|--------------|-------|
| | 3.0V to 3.6V | 2.3V to 2.7V | 1.65V to 1.95V | 1.4V to 1.6V | 1.1V to 1.3V | |
| | Min. | Min. | Min. | Min. | Typ. | |
| 3.0V to 3.6V | 140 | 120 | 100 | 80 | 40 | Mbps |
| 2.3V to 2.7V | 120 | 120 | 100 | 80 | 40 | Mbps |
| 1.65V to 1.95V | 100 | 100 | 80 | 60 | 40 | Mbps |
| 1.4V to 1.6V | 80 | 80 | 60 | 60 | 40 | Mbps |
| | Typ. | Typ. | Typ. | Typ. | Typ. | |
| 1.1V to 1.3V | 40 | 40 | 40 | 40 | 40 | Mbps |

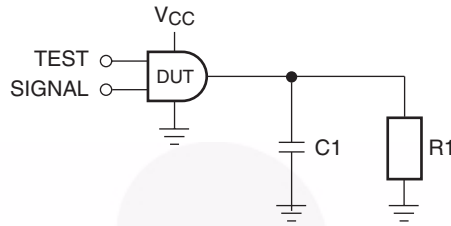
Note:

12. Max Data Rate is guaranteed but not tested.

13. Max Data Rate is specified in megabits per second. See Figure 7. It is equivalent to two times the F-toggle frequency, specified in megahertz. For example, 100 Mbps is equivalent to 50 MHz.

Capacitance

| Symbol | Parameter | Conditions | $T_A = +25^{\circ}C$ | Units |
|-----------|--|---|----------------------|-------|
| | | | Typical | |
| C_{in} | Input Capacitance, Control pin (\overline{OE}) | $V_{CCA} = V_{CCB} = GND$ | 3 | pF |
| $C_{i/o}$ | Input/Output Capacitance | An | 4 | pF |
| | | Bn | | |
| C_{pd} | Power Dissipation Capacitance | $V_{CCA} = V_{CCB} = 3.3V$, $V_i = 0V$ or V_{CC} , $f = 10MHz$ | 25 | pF |

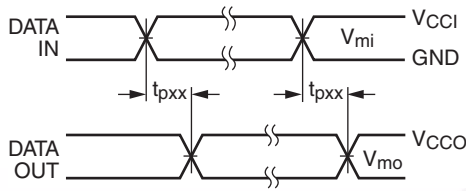


| Test | Input Signal | Output Enable Control |
|-----------------------|--------------|-----------------------|
| t_{PLH} , t_{PHL} | Data Pulses | 0V |
| t_{PZL} | 0V | HIGH to LOW Switch |
| t_{PZH} | V_{CCI} | HIGH to LOW Switch |

Figure 1. AC Test Circuit

AC Load Table

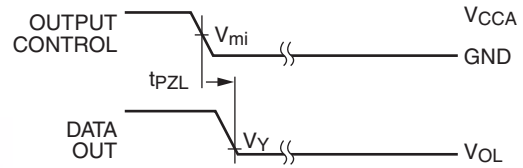
| V_{CC0} | CI | RI |
|------------------|------|------------|
| $1.2V \pm 0.1V$ | 15pF | $1M\Omega$ |
| $1.5V \pm 0.1V$ | 15pF | $1M\Omega$ |
| $1.8V \pm 0.15V$ | 15pF | $1M\Omega$ |
| $2.5V \pm 0.2V$ | 15pF | $1M\Omega$ |
| $3.3 \pm 0.3V$ | 15pF | $1M\Omega$ |



Input $t_R = t_F = 2.0\text{ns}$, 10% to 90%

Input $t_R = t_F = 2.5\text{ns}$, 10% to 90%, @ $V_i = 3.0\text{V}$ to 3.6V only

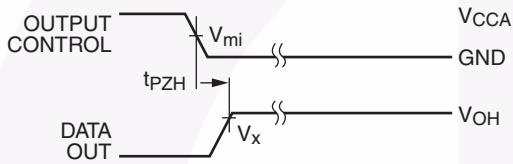
Figure 2. Waveform for Inverting and Non-inverting Functions



Input $t_R = t_F = 2.0\text{ns}$, 10% to 90%

Input $t_R = t_F = 2.5\text{ns}$, 10% to 90%, @ $V_i = 3.0\text{V}$ to 3.6V only

Figure 3. 3-STATE Output Low Enable Time for LOW Voltage Logic



Input $t_R = t_F = 2.0\text{ns}$, 10% to 90%

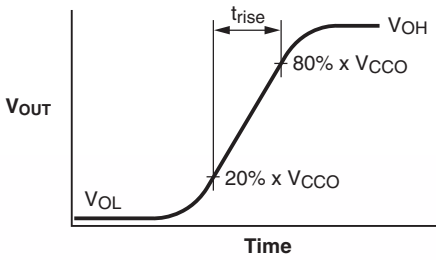
Input $t_R = t_F = 2.5\text{ns}$, 10% to 90%, @ $V_i = 3.0\text{V}$ to 3.6V only

Figure 4. 3-STATE Output High Enable Time for LOW Voltage Logic

| Symbol | V_{CC} |
|-----------------|----------------------|
| $V_{mi}^{(14)}$ | $V_{CCI} / 2$ |
| V_{mo} | $V_{CCO} / 2$ |
| V_X | $0.9 \times V_{CCO}$ |
| V_Y | $0.1 \times V_{CCO}$ |

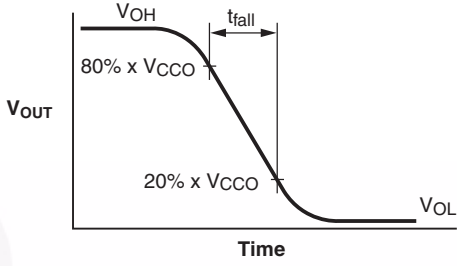
Note:

14. $V_{CCI} = V_{CCA}$ for control pin \overline{OE} or $V_{mi} = (V_{CCA} / 2)$.



$$I_{OHD} \approx (C_L + C_{I/O}) \times \frac{\Delta V_{OUT}}{\Delta t} = (C_L + C_{I/O}) \times \frac{(20\% - 80\%) \times V_{CCO}}{t_{RISE}}$$

Figure 5. Active Output Rise Time and Dynamic Output Current HIGH



$$I_{OLD} \approx (C_L + C_{I/O}) \times \frac{\Delta V_{OUT}}{\Delta t} = (C_L + C_{I/O}) \times \frac{(80\% - 20\%) \times V_{CCO}}{t_{FALL}}$$

Figure 6. Active Output Fall Time and Dynamic Output Current LOW

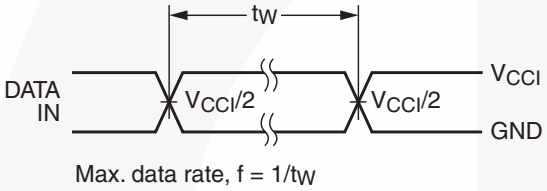
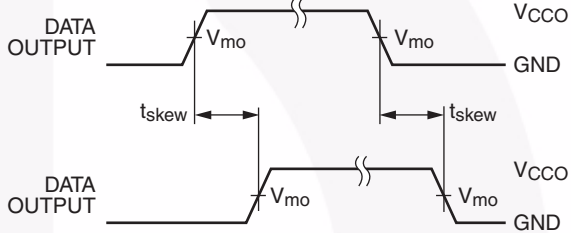


Figure 7. Maximum Data Rate



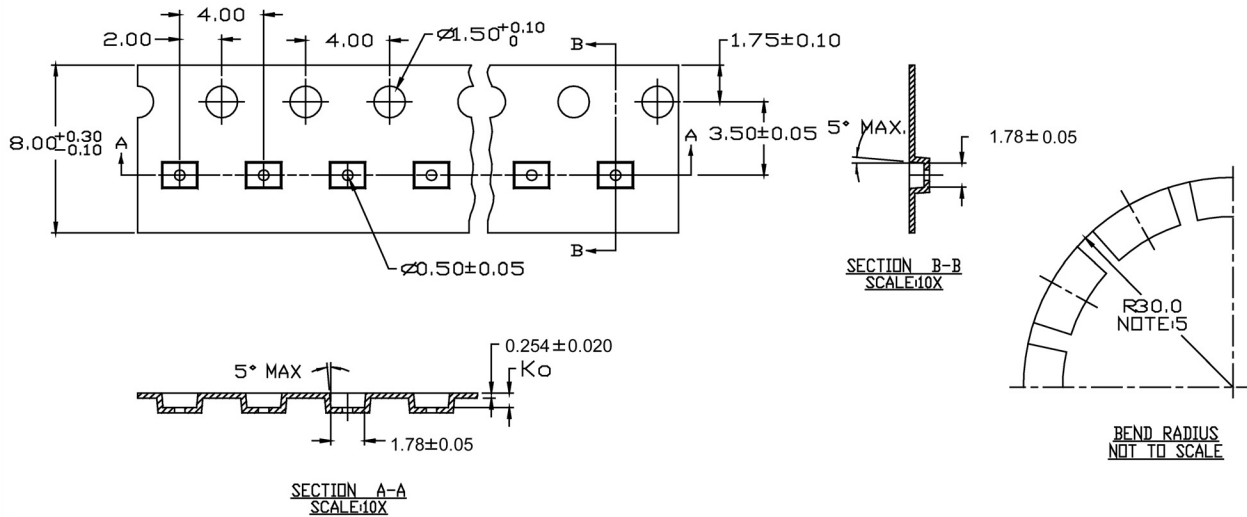
$$t_{skew} = (t_{pHLmax} - t_{pHLmin}) \text{ or } (t_{pLHmax} - t_{pLHmin})$$

Figure 8. Output Skew Time

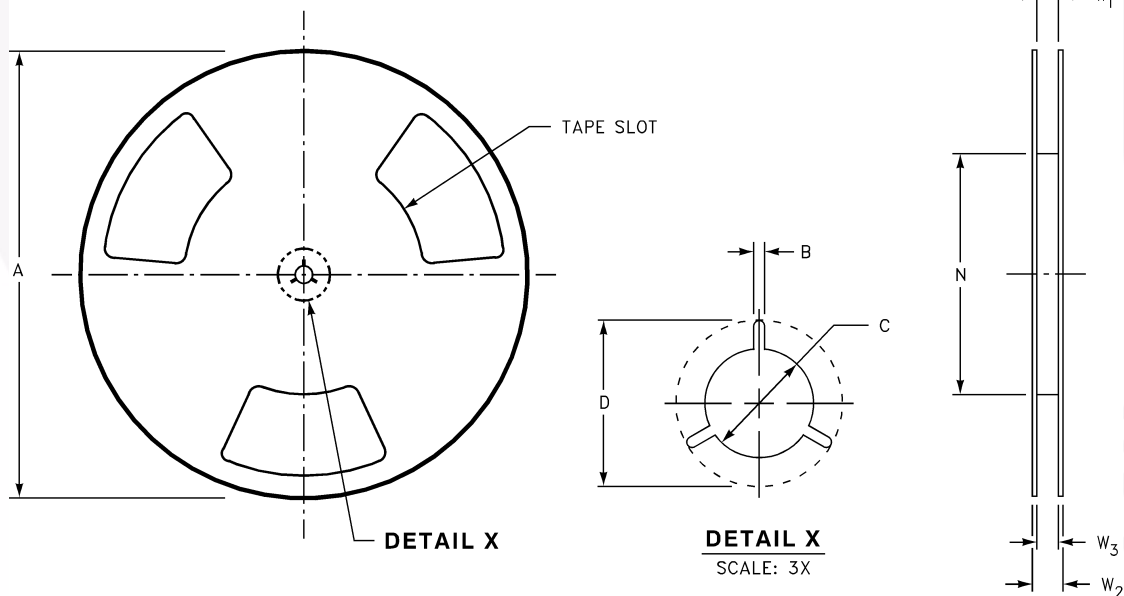
Tape and Reel Dimensions

| Package Designator | Tape Section | Number of Cavities | Cavity Status | Cover Tape Status |
|--------------------|--------------------|--------------------|---------------|-------------------|
| L8X | Leader (Start End) | 125 (typ.) | Empty | Sealed |
| | Carrier | 3000 | Filled | Sealed |
| | Trailer (Hub End) | 75 (typ.) | Empty | Sealed |

Tape Dimensions inches (millimeters)

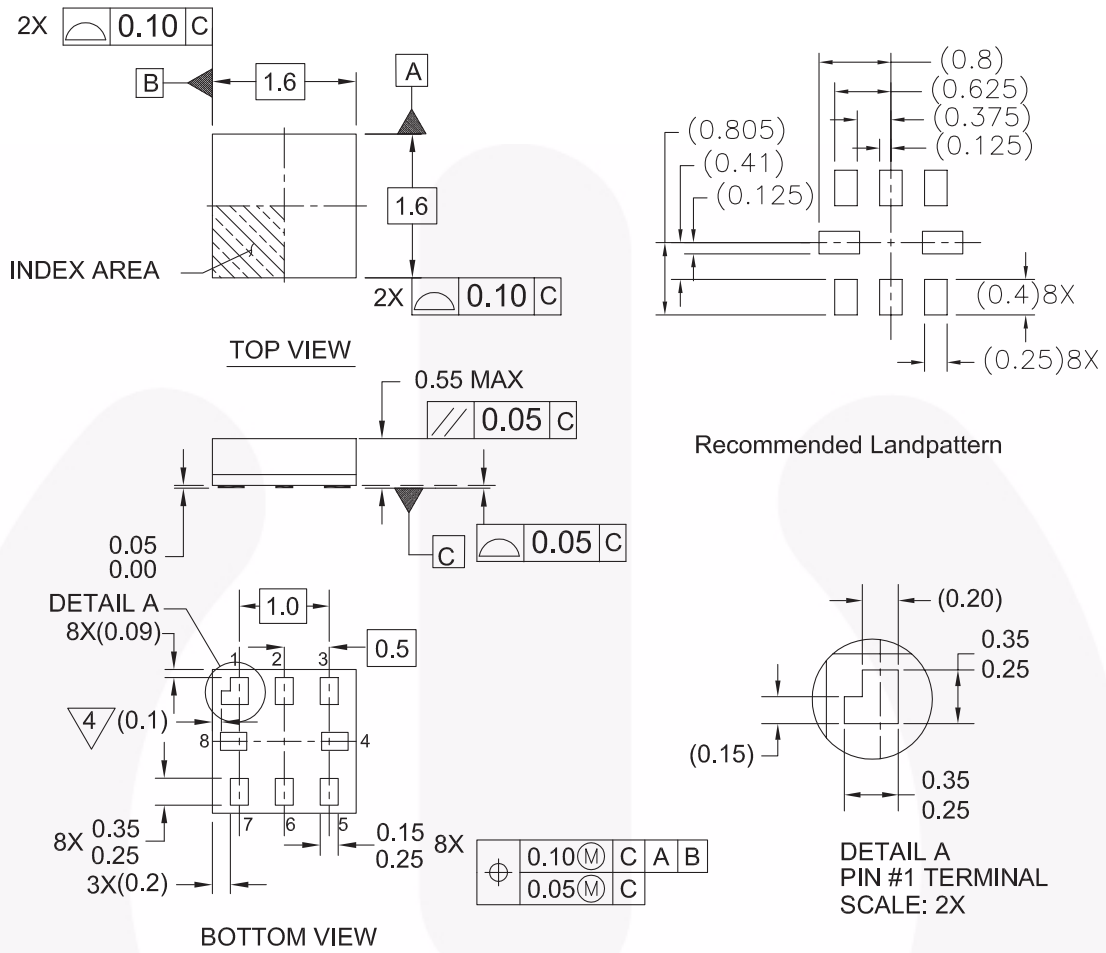


Reel Dimensions inches (millimeters)



| Tape Size | A | B | C | D | N | W1 | W2 | W3 |
|-----------|----------------|-----------------|------------------|------------------|------------------|---|------------------|--------------------------------------|
| 8mm | 7.0 (177.8) | 0.059 (1.50) | 0.512 (13.00) | 0.795 (20.20) | 2.165 (55.00) | 0.331 +0.059/-0.000 (8.40 +1.50/-0.00) | 0.567 (14.40) | W1 +0.078/-0.039 (W1 +2.00/-1.00) |

Physical Dimensions



Notes:

1. PACKAGE CONFORMS TO JEDEC MO-255 VARIATION UAAD
2. DIMENSIONS ARE IN MILLIMETERS
3. DRAWING CONFORMS TO ASME Y.14M-1994
4. PIN 1 FLAG, END OF PACKAGE OFFSET
5. DRAWING FILE NAME: MKT-MAC08AREV4

MAC08AREV4

Figure 9. 8-Lead MicroPak, 1.6mm Wide

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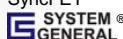
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